

# Forgetting and Uniform Interpolation in Multi-Agent Modal Logics

Liangda Fang<sup>1,3</sup>, Yongmei Liu<sup>1</sup> and Hans van Ditmarsch<sup>2</sup>

<sup>1</sup>Dept. of Computer Science, Sun Yat-sen University, China

<sup>2</sup>LORIA, CNRS – Université de Lorraine, France

<sup>3</sup>Dept. of Computer Science, Jinan University, China

Mar 24, 2018



# Introduction

- $\mathcal{P}$ : a finite set of propositions;
- $p \in \mathcal{P}$ ;
- $\varphi$ : the original formula;
- $\psi$ : a result of forgetting  $p$  in  $\varphi$ , *i.e.*, the strongest consequence of  $\varphi$  without  $p$ :
  - 1  $\psi$  does not contain  $p$ ;
  - 2 For any query  $\eta$  which does not contain  $p$ ,  $\varphi \models \eta$  iff  $\psi \models \eta$ .



# Introduction

- $\mathcal{P}$ : a finite set of propositions;
- $p \in \mathcal{P}$ ;
- $\varphi$ : the original formula;
- $\psi$ : a result of forgetting  $p$  in  $\varphi$ , *i.e.*, the strongest consequence of  $\varphi$  without  $p$ :
  - 1  $\psi$  does not contain  $p$ ;
  - 2 For any query  $\eta$  which does not contain  $p$ ,  $\varphi \models \eta$  iff  $\psi \models \eta$ .
- $\psi$ : the uniform interpolant of  $\phi$  on  $\mathcal{P} \setminus \{p\}$ .



# Introduction

- $\mathcal{P}$ : a finite set of propositions;
- $p \in \mathcal{P}$ ;
- $\varphi$ : the original formula;
- $\psi$ : a result of forgetting  $p$  in  $\varphi$ , *i.e.*, the strongest consequence of  $\varphi$  without  $p$ :
  - 1  $\psi$  does not contain  $p$ ;
  - 2 For any query  $\eta$  which does not contain  $p$ ,  $\varphi \models \eta$  iff  $\psi \models \eta$ .
- $\psi$ : the uniform interpolant of  $\phi$  on  $\mathcal{P} \setminus \{p\}$ .

How to compute  $\psi$ ?



# A brute-force approach to propositional logic

- 1 Transform  $\varphi$  into an equivalent principal DNF  $\bigvee_{t \in \Phi} t$ ;
- 2 Obtain  $t^p$  by eliminating any occurrence of  $p$  or  $\neg p$ ;
- 3  $\bigvee_{t \in \Phi} t^p$  is a result of forgetting  $p$  in  $\varphi$ .



# A brute-force approach to propositional logic

- 1 Transform  $\varphi$  into an equivalent principal DNF  $\bigvee_{t \in \Phi} t$ ;
- 2 Obtain  $t^p$  by eliminating any occurrence of  $p$  or  $\neg p$ ;
- 3  $\bigvee_{t \in \Phi} t^p$  is a result of forgetting  $p$  in  $\varphi$ .

## Example

- $\varphi = (p \wedge q) \vee (\neg p \wedge \neg r)$ ;
- $\varphi \equiv (\textcolor{red}{p} \wedge q \wedge r) \vee (\textcolor{red}{p} \wedge q \wedge \neg r) \vee (\neg \textcolor{red}{p} \wedge q \wedge \neg r) \vee (\neg \textcolor{red}{p} \wedge \neg q \wedge \neg r)$ ;
- $\psi = (q \wedge r) \vee (q \wedge \neg r) \vee (\neg q \wedge \neg r)$ .



# A brute-force approach to propositional logic

- 1 Transform  $\varphi$  into an equivalent principal DNF  $\bigvee_{t \in \Phi} t$ ;
- 2 Obtain  $t^p$  by eliminating any occurrence of  $p$  or  $\neg p$ ;
- 3  $\bigvee_{t \in \Phi} t^p$  is a result of forgetting  $p$  in  $\varphi$ .

## Example

- $\varphi = (p \wedge q) \vee (\neg p \wedge \neg r)$ ;
- $\varphi \equiv (\textcolor{red}{p} \wedge q \wedge r) \vee (\textcolor{red}{p} \wedge q \wedge \neg r) \vee (\textcolor{red}{\neg p} \wedge q \wedge \neg r) \vee (\textcolor{red}{\neg p} \wedge \neg q \wedge \neg r)$ ;
- $\psi = (q \wedge r) \vee (q \wedge \neg r) \vee (\neg q \wedge \neg r)$ .

How about multi-agent modal logics?

- Modal logic: propositional logic +  $\mathbf{K}_i$  operators;
- $\mathbf{K}_i\varphi$ : agent  $i$  knows  $\varphi$ .



# Outline

- 1 Introduction
- 2 Preliminaries
- 3 Forgetting
- 4 Conclusions and future work
- 5 Proof





# Outline

- 1 Introduction
- 2 Preliminaries
- 3 Forgetting
- 4 Conclusions and future work
- 5 Proof



# Modal language: $\mathcal{L}_C^K$

## Definition (Syntax of $\mathcal{L}_C^K$ )

$$\varphi ::= p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \mathbf{K}_i\varphi \mid \mathbf{C}\varphi,$$

where  $p \in \mathcal{P}$ ,  $i \in \mathcal{A}$ , and  $\varphi \in \mathcal{L}_C^K$ .



# Modal language: $\mathcal{L}_C^K$

## Definition (Syntax of $\mathcal{L}_C^K$ )

$$\varphi ::= p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \mathbf{K}_i\varphi \mid \mathbf{C}\varphi,$$

where  $p \in \mathcal{P}$ ,  $i \in \mathcal{A}$ , and  $\varphi \in \mathcal{L}_C^K$ .

## Definition (Two sublanguages)

- ①  $\mathcal{L}_n^K$ :  $\mathcal{L}_C^K$  without  $\mathbf{C}$  operator;
- ②  $\mathcal{L}_{PC}^K$ :  $\mathcal{L}_C^K$  with propositional common knowledge, *i.e.*, any  $\varphi$  appearing in  $\mathbf{C}\varphi$  must be propositional.



# Kripke models

## Definition (Kripke models)

A Kripke model is a tuple  $\langle S, R, V \rangle$  where

- $S$ : a non-empty set of states,
- $R$ : for each  $i \in \mathcal{A}$ ,  $R_i \subseteq S \times S$  is a relation on states.
- $V: S \rightarrow 2^{\mathcal{P}}$  is a function assigning to each proposition in a subset of states.

A pair  $(M, s)$  is called a pointed model.



# Kripke models

## Definition (Kripke models)

A Kripke model is a tuple  $\langle S, R, V \rangle$  where

- $S$ : a non-empty set of states,
- $R$ : for each  $i \in \mathcal{A}$ ,  $R_i \subseteq S \times S$  is a relation on states.
- $V: S \rightarrow 2^{\mathcal{P}}$  is a function assigning to each proposition in a subset of states.

A pair  $(M, s)$  is called a pointed model.

	L	K	D	T	K4	S4	K45	KD45	S5
Serial			✓	✓		✓		✓	✓
Reflexive				✓		✓			✓
Transitive					✓	✓	✓	✓	✓
Euclidean							✓	✓	✓



# Cover modalities

## Definition (Cover modalities)

- 1  $\nabla_i \Phi = \mathbf{K}_i(\bigvee_{\varphi \in \Phi} \varphi) \wedge \bigwedge_{\varphi \in \Phi} \hat{\mathbf{K}}_i \varphi;$
- 2  $\nabla \Phi = \mathbf{C}(\bigvee_{\varphi \in \Phi} \varphi) \wedge \bigwedge_{\varphi \in \Phi} \hat{\mathbf{C}} \varphi.$

where  $\hat{\mathbf{K}}_i \doteq \neg \mathbf{K}_i \neg$  and  $\hat{\mathbf{C}} \doteq \neg \mathbf{C} \neg$ .

We can use  $\nabla_i$  (resp.  $\nabla$ ) modality instead of  $\mathbf{K}_i$  (resp.  $\mathbf{C}$ ) modality.



# Canonical formulas

## Definition (Canonical formulas)

Let  $P \subseteq \mathcal{P}$  be finite. We inductively define the set  $E_k^P$  as follows:

- $E_0^P = \{\bigwedge_{p \in \mathcal{X}} p \wedge \bigwedge_{p \in P \setminus \mathcal{X}} \neg p \mid \mathcal{X} \subseteq P\};$
- $E_{k+1}^P = \{\delta_0 \wedge \bigwedge_{i \in \mathcal{A}} \nabla_i \Phi_i \mid \delta_0 \in E_0^P \text{ and } \Phi_i \subseteq E_k^P\}.$

$\delta_k \in E_k$ :

- completely characterizes a Kripke model up to depth  $k$ ;
- a minterm in modal logics.



# Canonical formulas

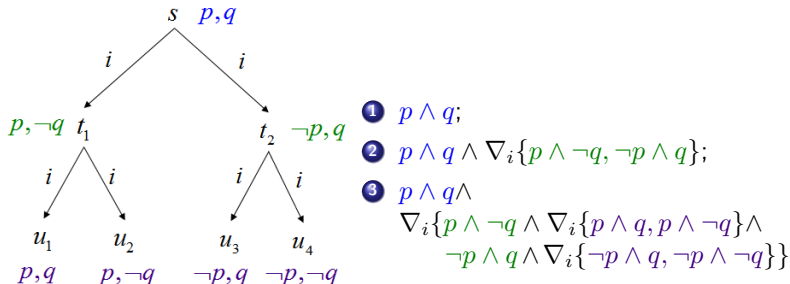


Figure: Kripke model





# Canonical formulas

## Proposition (Moss, 2007)

*Any formula in  $\mathcal{L}_n^K$  can be equivalently transformed into a disjunction of satisfiable canonical formulas.*



# Outline

- 1 Introduction
- 2 Preliminaries
- 3 Forgetting**
- 4 Conclusions and future work
- 5 Proof



# Computation of forgetting

- 1 Transform  $\varphi$  to a disjunction of **satisfiable canonical formulas**  
 $\bigvee_{\delta \in \Phi} \delta$ ;
- 2 Obtain  $\delta^p$  by eliminating any occurrence of  $p$  or  $\neg p$ ;
- 3  $\bigvee_{\delta \in \Phi} \delta^p$  is a result of forgetting  $p$  in  $\varphi$ .



# Computation of forgetting

- 1 Transform  $\varphi$  to a disjunction of **satisfiable canonical formulas**  
 $\bigvee_{\delta \in \Phi} \delta$ ;
- 2 Obtain  $\delta^p$  by eliminating any occurrence of  $p$  or  $\neg p$ ;
- 3  $\bigvee_{\delta \in \Phi} \delta^p$  is a result of forgetting  $p$  in  $\varphi$ .

## Example

- $\varphi = \hat{\mathbf{K}}_i p \wedge \hat{\mathbf{K}}_i \neg p$ ;
- $\varphi \equiv \delta_1 \vee \delta_2$ ;
- $\delta_1 = p \wedge \nabla_i \{p, \neg p\}$ ;
- $\delta_2 = \neg p \wedge \nabla_i \{p, \neg p\}$ ;
- $\delta_1^p \vee \delta_2^p \equiv \top \wedge \nabla_i \{\top\} \equiv \hat{\mathbf{K}}_i \top$ .



# Main theorem

## Theorem

*Let  $L$  be  $K_n$ ,  $D_n$ ,  $T_n$ ,  $K45_n$ ,  $KD45_n$  or  $S5_n$ .*

*Let  $\delta$  be a canonical formula satisfiable in  $L$ .*

*Then,  $\delta^p$  is a result of forgetting  $p$  in  $\delta$ .*



# Main theorem

## Theorem

*Let  $L$  be  $K_n$ ,  $D_n$ ,  $T_n$ ,  $K45_n$ ,  $KD45_n$  or  $S5_n$ .*

*Let  $\delta$  be a canonical formula satisfiable in  $L$ .*

*Then,  $\delta^p$  is a result of forgetting  $p$  in  $\delta$ .*

## Corollary

*$K_n$ ,  $D_n$ ,  $T_n$ ,  $K45_n$ ,  $KD45_n$  and  $S5_n$  are closed under forgetting.*



# Main theorem

## Definition (Uniform interpolation)

A logic  $L$  has uniform interpolation: In the logic  $L$ , for any formula  $\varphi$  and any proposition  $p$ , there is a formula  $\psi$  that is a uniform interpolant of  $\varphi$  on  $\mathcal{P} \setminus p$ .



# Main theorem

## Definition (Uniform interpolation)

A logic  $L$  has uniform interpolation: In the logic  $L$ , for any formula  $\varphi$  and any proposition  $p$ , there is a formula  $\psi$  that is a uniform interpolant of  $\varphi$  on  $\mathcal{P} \setminus p$ .

## Corollary

$K_n$ ,  $D_n$ ,  $T_n$ ,  $K45_n$ ,  $KD45_n$  and  $S5_n$  have uniform interpolation.





# Common knowledge case

- Negative result: KC is not closed under forgetting. [Studer, 2009]
- We consider the propositional common knowledge case, *i.e.*,  $\mathcal{L}_{PC}^K$  where any  $\varphi$  appearing in  $C\varphi$  must be propositional.



# Pc-canonical formulas

## Definition (Pc-canonical formulas)

Let  $P \subseteq \mathcal{P}$  be finite. We inductively define the set  $C_k^P$  as follows:

- $C_0^P = \{\theta \wedge \nabla \Phi_{\mathcal{A}} \mid \theta \in E_0^P \text{ and } \Phi_{\mathcal{A}} \subseteq E_0^P\};$
- $C_{k+1}^P = \{\theta \wedge (\bigwedge_{i \in \mathcal{A}} \nabla_i \Phi_i) \wedge \nabla \Phi_{\mathcal{A}} \mid \theta \in E_0^P, \Phi_i \subseteq C_k^P \text{ and } \Phi_{\mathcal{A}} \subseteq E_0^P\}.$



# Pc-canonical formulas

## Definition (Pc-canonical formulas)

Let  $P \subseteq \mathcal{P}$  be finite. We inductively define the set  $C_k^P$  as follows:

- $C_0^P = \{\theta \wedge \nabla \Phi_{\mathcal{A}} \mid \theta \in E_0^P \text{ and } \Phi_{\mathcal{A}} \subseteq E_0^P\};$
- $C_{k+1}^P = \{\theta \wedge (\bigwedge_{i \in \mathcal{A}} \nabla_i \Phi_i) \wedge \nabla \Phi_{\mathcal{A}} \mid \theta \in E_0^P, \Phi_i \subseteq C_k^P \text{ and } \Phi_{\mathcal{A}} \subseteq E_0^P\}.$

## Proposition

*Any formula in  $\mathcal{L}_{\text{PC}}^{\mathbf{K}}$  can be equivalently transformed into a disjunction of satisfiable pc-canonical formulas.*



# Main theorem 2

## Theorem

*Let  $L$  be KC, DC, TC, K45C, KD45C or S5C.*

*Let  $\delta$  be a pc-canonical formula satisfiable in  $L$ .*

*Then,  $\delta^p$  is a result of forgetting  $p$  in  $\delta$ .*

## Corollary

*KPC, DPC, TPC, K45PC, KD45PC and S5PC are closed under forgetting, and have uniform interpolation.*



# Conclusions

- Prove that  $K_n$ ,  $D_n$ ,  $T_n$ ,  $K45_n$ ,  $KD45_n$  and  $S5_n$  are closed under forgetting.
- Extend the above results to propositional common knowledge case.



# Current Results

L	K	D	T	K4	S4	K45	KD45	S5
$\mathcal{L}_1^K$	$\checkmark^1$	$\checkmark^7$	$\checkmark^5$	$\times^5$	$\times^2$	$\checkmark$	$\checkmark$	$\checkmark^3$
$\mathcal{L}_n^K$	$\checkmark^4$	$\checkmark^7$	$\checkmark^{3,5}$	$\times^5$	$\times^2$	$\checkmark$	$\checkmark$	$\checkmark^3$
$\mathcal{L}_{PC}^K$	$\checkmark$	$\checkmark$	$\checkmark$	$\times^5$	$\times^2$	$\checkmark$	$\checkmark$	$\checkmark$
$\mathcal{L}_C^K$	$\times^6$	?	?	$\times^5$	$\times^2$	?	?	?

- ① [Ghilardi, 1995]
- ② [Ghilardi and Zawadowski, 1995]
- ③ [Wolter, F., 1998]
- ④ [D'Agostino and Lenzi, 2005]
- ⑤ [Bílková, 2007]
- ⑥ [Studer, 2009]
- ⑦ [Pattinson, 2013]



# Future work

- ❶ A practical approach for computing forgetting;
  - Identify a tractable form (DNF counterpart of modal logics);
  - Resolution methods: [Herzig and Mengin, 2008].



# Future work

- ❶ A practical approach for computing forgetting;
  - Identify a tractable form (DNF counterpart of modal logics);
  - Resolution methods: [Herzig and Mengin, 2008].
- ❷ More general cases of common knowledge: any  $\varphi$  appearing in  $\mathbf{C}\varphi$  can be in  $\mathcal{L}_n^K$ ;





# Future work

- ❶ A practical approach for computing forgetting;
  - Identify a tractable form (DNF counterpart of modal logics);
  - Resolution methods: [Herzig and Mengin, 2008].
- ❷ More general cases of common knowledge: any  $\varphi$  appearing in  $C\varphi$  can be in  $\mathcal{L}_n^K$ ;
- ❸ Distributed knowledge: the sum of the knowledge in a group
  - $K_D$ ,  $D_D$  and  $T_D$ : ✓;
  - $K45_D$ ,  $KD45_D$  and  $S5_D$ : ?



# Future work

- ❶ A practical approach for computing forgetting;
  - Identify a tractable form (DNF counterpart of modal logics);
  - Resolution methods: [Herzig and Mengin, 2008].
- ❷ More general cases of common knowledge: any  $\varphi$  appearing in  $\mathbf{C}\varphi$  can be in  $\mathcal{L}_n^{\mathbf{K}}$ ;
- ❸ Distributed knowledge: the sum of the knowledge in a group
  - $\mathbf{K}_D$ ,  $\mathbf{D}_D$  and  $\mathbf{T}_D$ : ✓;
  - $\mathbf{K}45_D$ ,  $\mathbf{KD}45_D$  and  $\mathbf{S5}_D$ : ?
- ❹ Monotone Modal Logic:  $\mathbf{K}_i(p \wedge q) \rightarrow \mathbf{K}_ip$ 
  - $\mathbf{M}$ : ✓ [Santocanale and Venema, 2010];
  - $\mathbf{M}$  extended by classical axioms: ?.



# Future work

- ① A practical approach for computing forgetting;
  - Identify a tractable form (DNF counterpart of modal logics);
  - Resolution methods: [Herzig and Mengin, 2008].
- ② More general cases of common knowledge: any  $\varphi$  appearing in  $\mathbf{C}\varphi$  can be in  $\mathcal{L}_n^K$ ;
- ③ Distributed knowledge: the sum of the knowledge in a group
  - $\mathbf{K}_D$ ,  $\mathbf{D}_D$  and  $\mathbf{T}_D$ : ✓;
  - $\mathbf{K}45_D$ ,  $\mathbf{KD}45_D$  and  $\mathbf{S5}_D$ : ?
- ④ Monotone Modal Logic:  $\mathbf{K}_i(p \wedge q) \rightarrow \mathbf{K}_ip$ 
  - $\mathbf{M}$ : ✓ [Santocanale and Venema, 2010];
  - $\mathbf{M}$  extended by classical axioms: ?.
- ⑤ Progression and diagnose in multi-agent settings.
  - Progression in the Situation Calculus: [Fang, *et al.*, 2015];
  - Diagnose in propositional logic: [Lin, 2001] and [Lang, 2008].



# Thank you!



# Outline

- 1 Introduction
- 2 Preliminaries
- 3 Forgetting
- 4 Conclusions and future work
- 5 Proof**

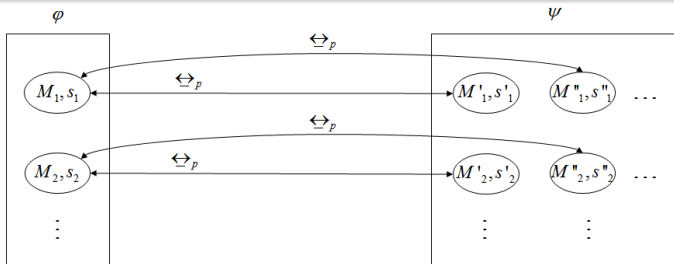


# Model-theoretic definition of forgetting

## Definition

Consider the context of a modal system  $L$ . Let  $\varphi \in \mathcal{L}_C^K$ . We call  $\psi$  is the result of forgetting  $p$  from  $\varphi$ , if the following conditions hold:

- Forth: for any model  $(M, s)$  of  $\varphi$ , if  $(M', s')$  is a model s.t.  $(M, s) \Leftrightarrow_p (M', s')$ , then  $M', s' \models \psi$ ; (Easy: by induction)
- Back: for any model  $(M', s')$  of  $\psi$ , there exists a model  $(M, s)$  s.t.  $M, s \models \varphi$  and  $(M, s) \Leftrightarrow_p (M', s')$ . (Very difficult!)



# Proof of back condition

- $(M', s')$ : an L-model of  $\delta^p$ ;
- Construct  $(M, s)$  s.t.
  - ❶  $(M, s)$  is an L-model;
  - ❷  $M, s \models \varphi$ ;
  - ❸  $(M, s) \xleftrightarrow{p} (M', s')$ .
- $\delta \in E_0$ :
  - ❶ Let  $(M, s)$  be the copy  $(M', s')$ .
  - ❷ Modify the valuation on  $s$  s.t.  $V'(s') \models \delta$ .
- $\delta \in E_{k+1}$ :  $\delta = \theta \wedge \bigwedge_{i \in A} \nabla_i \Phi_i$ . By induction?



# $K_n$ and $D_n$ : by induction

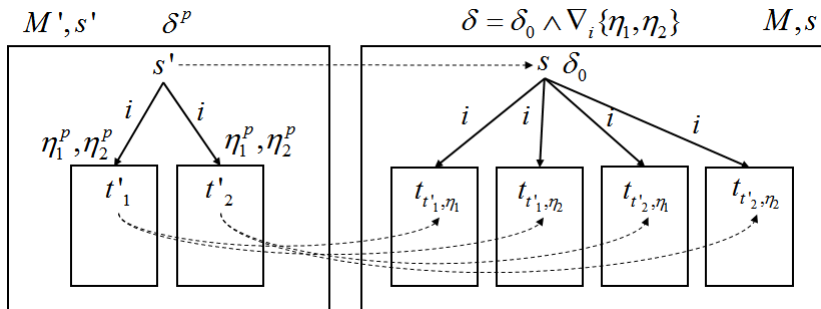


Figure: Illustration for the proof of  $K_n$  and  $D_n$  cases





# $T_n$ : add reflexive edge

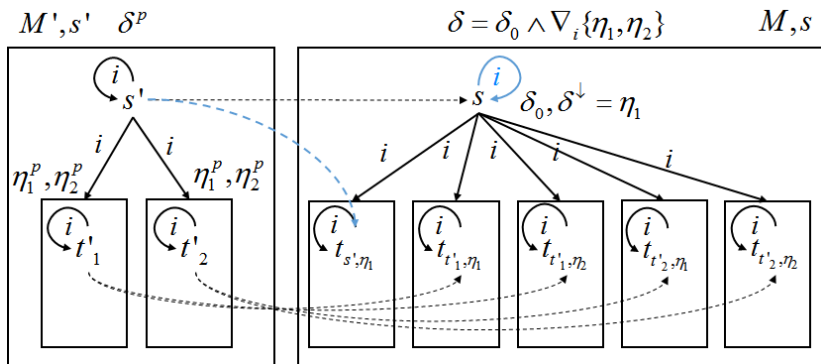


Figure: Illustration for the proof of  $T_n$  case



# K45<sub>n</sub> and KD45<sub>n</sub>: multi-pointed models

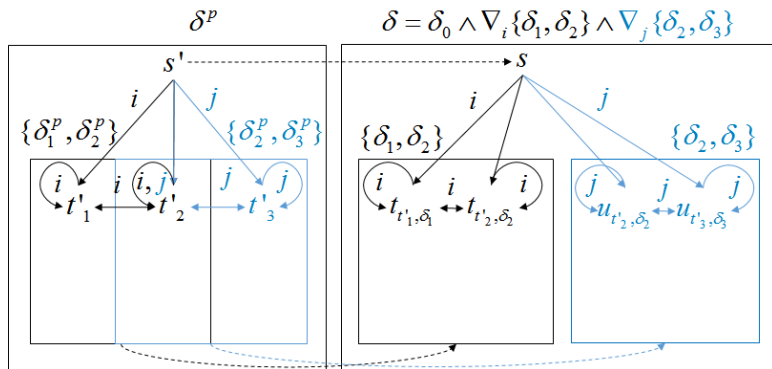


Figure: Illustration for the proof of K45<sub>n</sub> and KD45<sub>n</sub> cases



# K45<sub>n</sub> and KD45<sub>n</sub>: multi-pointed models

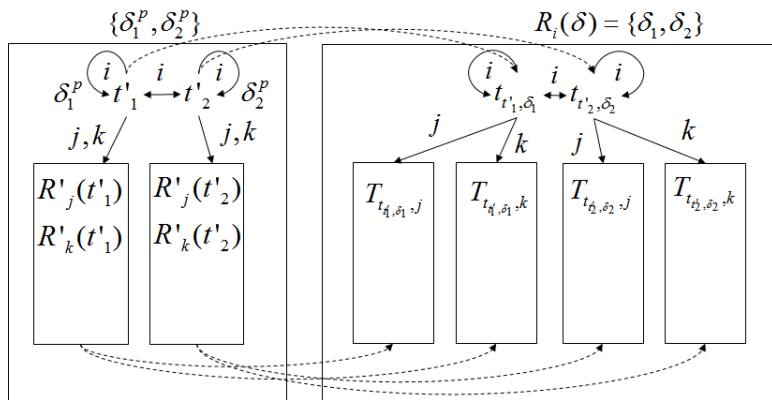


Figure: Illustration for the proof of K45<sub>n</sub> and KD45<sub>n</sub> cases



# S5<sub>n</sub>: add reflexive and symmetric edges

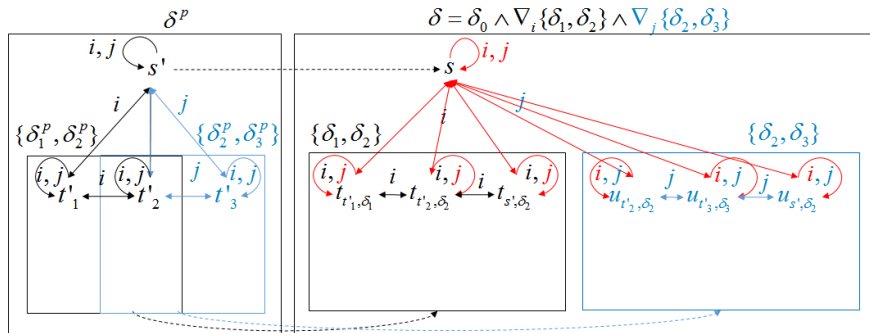


Figure: Illustration for the proof of S5<sub>n</sub> case



# S5<sub>n</sub>: add reflexive and symmetric edges

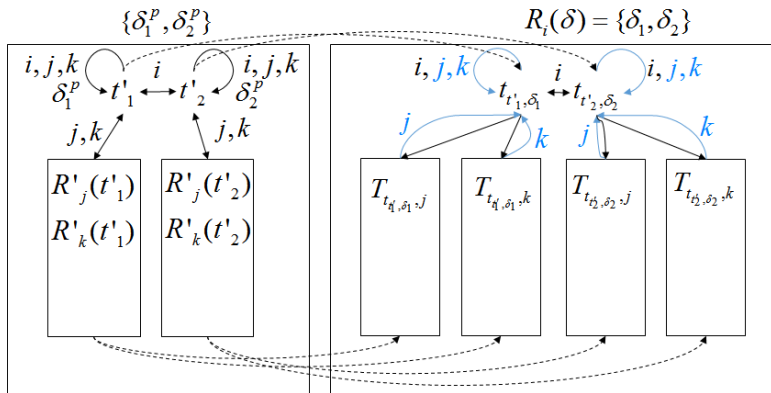


Figure: Illustration for the proof of S5<sub>n</sub> case



# Extension to $\mathcal{L}_{PC}^K$ : split a world into several copies

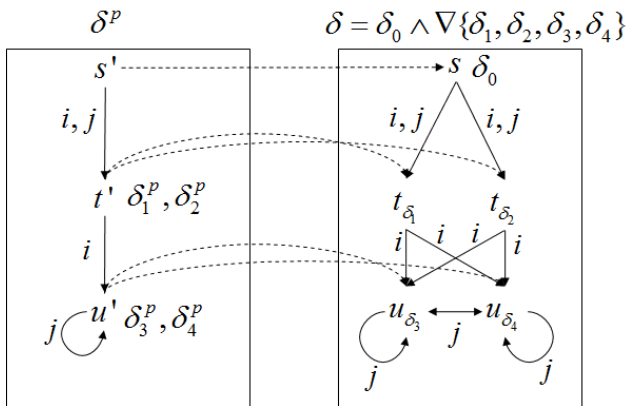


Figure: Illustration for the proof of KPC basic case

